

HYDRAULIC CONTROL SYSTEM AND METHOD FOR BELT-DRIVE  
CONTINUOUSLY VARIABLE TRANSMISSION

BACKGROUND OF THE INVENTION

[0001] The present invention relates to a hydraulic  
5 control system and method for a belt-drive continuously  
variable transmission (CVT).

[0002] One example of such a hydraulic control system is  
known, which includes an oil pump and a pressure regulator  
valve coupled with the oil pump. The pressure regulator  
10 valve adjusts a hydraulic pressure as a pulley clamping  
pressure which is discharged from the oil pump. A clutch  
regulator valve disposed on the downstream side of the  
pressure regulator valve adjusts a hydraulic pressure to be  
supplied to a select switching valve. A torque converter  
15 regulator valve disposed on the downstream side of the  
clutch regulator valve adjusts a hydraulic pressure to be  
supplied to a lockup control valve. An oil cooler for  
maintaining oil at a constant temperature is disposed on the  
downstream side of the torque converter regulator valve. A  
20 lubricating oil supply member, for example, an oil supply  
nozzle, for supplying the oil for lubricating the belt of  
the CVT is disposed on the downstream side of the oil cooler.  
In the belt-drive CVT, an oil amount leaking from  
lubrication parts of the CVT increases under high oil  
25 temperature condition. This will prevent the oil from being  
supplied in a sufficient amount through the oil supply  
nozzle. In order to maintain a required flow amount of the  
belt lubricating oil at high oil temperature, a conventional  
art controls oil pump speed, namely, engine speed, by  
30 controlling a transmission ratio of the CVT based on a  
predetermined flow amount of the oil discharged from the oil  
pump which is set corresponding to each oil temperature.

SUMMARY OF THE INVENTION

[0003] An oil amount required for lubricating the belt of the CVT is usually varied depending on operating conditions of a pulley ratio of the belt-drive CVT, vehicle speed, 5 input torque and the like. Therefore, the conventional art which determines an oil flow amount discharged from the oil pump on the basis of only the oil temperature, must determine a required maximum oil flow amount at each oil temperature. This will cause excessive increase in the oil 10 flow amount discharged from the oil pump to thereby enhance the engine speed, resulting in deterioration in fuel economy. Further, in a case where the engine speed is excessively increased, engine brake effect will not be sufficiently performed and vehicle drivability will be deteriorated.

15 [0004] It is an object of the present invention to eliminate the above-described disadvantages and provide a hydraulic control system and method for a belt-drive continuously variable transmission (CVT), which is capable of determining an appropriate oil flow amount required for 20 lubricating a belt of the CVT on the basis of vehicle operating conditions and capable of restricting an unnecessary oil flow amount for the lubrication, serving for reducing the engine speed in high oil temperature condition.

[0005] In one aspect of the present invention, there is 25 provided a hydraulic control system for a belt-drive continuously variable transmission (CVT) of a vehicle, the CVT including a belt, the hydraulic control system comprising:

an oil pump operative to produce an oil pressure and an 30 oil flow amount which are supplied to the CVT;

a pressure regulator valve operative to regulate the oil pressure produced by the oil pump;

a belt lubricating oil supply passage for supplying oil to the belt on a downstream side of the pressure regulator valve;

5 engine operating condition detecting means for detecting an engine operating condition and generating a signal indicative of the engine operating condition detected; and

a controller for controlling the oil flow amount based on the signal, the controller being programmed to:

calculate a CVT input torque based on the signal;

10 calculate a required belt lubricating oil flow amount to be supplied to the belt on the basis of the signal and the CVT input torque;

determine a minimum speed of the oil pump based on the required belt lubricating oil flow amount; and

15 control the oil pump at the minimum speed.

[0006] In another aspect of the invention, there is provided a method for controlling a belt-drive continuously variable transmission (CVT) of a vehicle, the CVT including a belt, the vehicle including an oil pump operative to  
20 produce an oil pressure and an oil flow amount which are supplied to the CVT, a pressure regulator valve operative to regulate the oil pressure produced by the oil pump, and a belt lubricating oil supply passage on a downstream side of the pressure regulator valve, the method comprising:

25 generating an engine operating condition signal indicative of an engine operating condition;

calculating a CVT input torque based on the engine operating condition signal;

30 calculating a required belt lubricating oil flow amount to be supplied to the belt on the basis of the engine operating condition signal and the CVT input torque;

determining a minimum speed of the oil pump based on the required belt lubricating oil flow amount; and

controlling the oil pump at the minimum speed.

**BRIEF DESCRIPTION OF THE DRAWINGS**

[0007] FIG. 1 is a schematic diagram illustrating a control system of an automatic transmission equipped with a belt-drive continuously variable transmission (CVT), according to a first embodiment of the present invention.

[0008] FIG. 2 is a hydraulic circuit diagram of the CVT of Fig. 1.

[0009] FIG. 3 is a flow chart of a routine of determining oil pump speed which is executed in the first embodiment.

[0010] FIG. 4 is a table for selecting a map used for calculation of a required belt lubricating oil flow amount.

[0011] FIG. 5 is a map showing a relationship between required oil flow amount and primary pulley speed.

[0012] FIG. 6 is a map showing a relationship between cooler oil flow amount and cooler input pressure corresponding to line pressure.

[0013] FIG. 7 is a map showing a relationship between cooler input pressure and oil pump minimum speed at different oil temperatures and line pressures.

[0014] FIG. 8 is a map showing a relationship between required belt lubricating oil flow amount and CVT input torque.

[0015] FIG. 9 is a map showing a relationship between required belt lubricating oil flow amount and pulley speed ratio.

[0016] FIG. 10 is a map used in a second embodiment of the present invention, showing a relationship between cooler input pressure and oil pump minimum speed in a manual transmission mode and an automatic transmission mode.

[0017] FIG. 11 is a flow chart of a routine of determining oil pump minimum speed which is executed in the second embodiment.

DETAILED DESCRIPTION OF THE INVENTION

[0018] Referring to FIG. 1, there is shown a hydraulic control system for belt-drive continuously variable transmission (CVT) 3, according to a first embodiment of the present invention. As illustrated in FIG. 1, CVT 3 is coupled to an engine via lockup clutch 2 for direct connection between CVT 3 and the engine. Torque converter 1 is connected to output shaft 12 of the engine. Forward-reverse switching mechanism 20 is disposed on an output side of torque converter 1. Forward-reverse switching mechanism 20 includes a planetary gear train, reverse brake 24 and forward clutch 25. The planetary gear train includes ring gear 21 coupled to output shaft 12 of the engine, pinion carrier 22, and sun gear 23 coupled to input shaft 13 of CVT 3. Reverse brake 24 is operative to fix pinion carrier 22 to a transmission case. Forward clutch 25 is operative to couple input shaft 13 of CVT 3 and pinion carrier 22 with each other. Oil pump 8 is mechanically coupled to the engine and directly driven by the engine.

[0019] CVT 3 includes primary pulley 30a, secondary pulley 30b and belt 34 connecting primary and secondary pulleys 30a and 30b to thereby transmit the rotation force of primary pulley 30a to secondary pulley 30b. Primary pulley 30a is disposed on a rear end portion of input shaft 13. Primary pulley 30a includes fixed disk 31 rotatable together with input shaft 13, and moveable disk 32 opposed to fixed disk 31 in an axial direction of input shaft 13. Fixed and moveable disks 31 and 32 have generally conical shapes and cooperate with each other to form a V-groove in which belt 34 is engaged. Moveable disk 32 is axially moved on input shaft 13 by an oil pressure supplied to primary pulley cylinder chamber 33. Secondary pulley 30b is disposed on driven shaft 38. Secondary pulley 30b includes fixed

conical disk 35 rotatable together with driven shaft 38, and moveable disk 36 opposed to fixed disk 35 in an axial direction of driven shaft 38. Fixed and moveable disks 35 and 36 have generally conical shapes and cooperate with each other to form a V-groove in which belt 34 is engaged. Moveable disk 36 is axially moved on driven shaft 38 by an oil pressure supplied to secondary pulley cylinder chamber 37. A driving gear, not shown, is fixed onto driven shaft 38. The driving gear is operative to drive a driving shaft connected to a wheel, via a pinion on an idler shaft, a final gear and a differential gear.

[0020] The rotation force outputted from output shaft 12 of the engine is transmitted to input shaft 13 of CVT 3 via torque converter 1 and forward-reverse switching mechanism 20. The rotation force of input shaft 13 is successively transmitted to primary pulley 30a, belt 34, secondary pulley 30b, driven shaft 38, the driving gear, an idler gear, the idling shaft, the pinion, the final gear and the differential gear. Upon thus transmitting the rotation force, moveable disk 32 of primary pulley 30a and moveable disk 36 of secondary pulley 30b are axially moved on input and driven shafts 13 and 38, respectively, to change a width of the V-groove which extends in the axial direction of input and driven shafts 13 and 38. A radius of curvature of a circular arc formed by V-belt 34 contacted with pulleys 30a and 30b is continuously varied by changing the V-groove width. A pulley speed ratio between the rotational speed of primary pulley 30a and the rotational speed of secondary pulley 30b, namely, a transmission ratio of CVT 3, can be thus changed. The change of the V-groove width is conducted by controlling the oil pressure supplied to primary pulley cylinder chamber 33 and secondary pulley cylinder chamber 37.



The hydraulic control is performed by CVT control unit or controller 9.

[0021] A plurality of sensors are electronically connected to CVT controller 9 and detect engine operating conditions. The sensors includes primary pulley speed sensor 4, secondary pulley speed sensor 5, throttle position sensor 10, oil temperature sensor 11, pulley clamping pressure sensor 14, line pressure sensor 15, transmission mode sensor 16, and anti-lock brake system (ABS) sensor 17.

Primary pulley speed sensor 4 detects the rotational speed of primary pulley 30a and generates signal Np indicative of the detected primary pulley speed. Secondary pulley speed sensor 5 detects the rotational speed of secondary pulley 30b and generates signal Ns indicative of the detected secondary pulley speed. Throttle position sensor 10 detects an opening degree of a throttle valve and generates signal TVO indicative of the detected throttle opening degree. Oil temperature sensor 11 detects a temperature of the oil in CVT 3 and generates signal Toil indicative of the detected oil temperature. Pulley clamping pressure sensor 14 detects a pulley clamping pressure supplied to each of primary and secondary pulley cylinder chambers 33 and 37 so as to clamp belt 34, and generates signal CP indicative of the detected pulley clamping pressure. Line pressure sensor 15 detects a line pressure and generates signal LP indicative of the detected line pressure. Transmission mode sensor 16 detects a manual transmission mode or an automatic transmission mode which is selected based on a position of a transmission mode selector switch provided on a shift lever, not shown. The manual transmission mode allows to manually change the pulley speed ratio. The automatic transmission mode allows to automatically change the pulley speed ratio. Transmission mode sensor 16 generates manual mode signal MM

when the manual transmission mode is selected, and automatic mode signal AM when the automatic transmission mode is selected. ABS sensor 17 detects whether or not ABS is in operation and generates ABS control signal ABS control  
5 ON/OFF indicative of the ABS in operation or out of operation. ABS includes a wheel speed sensor, not shown, G sensor, not shown, ABS actuator 18 for controlling a braking pressure, and ABS control unit 19 for generating a control signal to ABS actuator 18 based on the detected wheel speed  
10 and acceleration.

[0022] CVT controller 9 receives the signals generated from these sensors, processes the signals, and develops and transmits control signal CS to hydraulic control valve unit 6. As explained in detail later, CVT controller 9 is  
15 programmed to calculate CVT input torque  $T_{Qin}$  based on throttle opening degree signal TVO, calculate required belt lubricating oil flow amount  $Q_{br}$  to be supplied to belt 34 on the basis of oil temperature signal  $T_{oil}$  and CVT input torque  $T_{Qin}$ , determine oil pump minimum speed  $N_{min}$  based on  
20 required belt lubricating oil flow amount  $Q_{br}$ , and control oil pump 8 at minimum speed  $N_{min}$ . CVT controller 9 may be a microcomputer including central processing unit (CPU), input and output ports (I/O), read-only memory (ROM), random access memory (RAM) and a common data bus.

25 [0023] Hydraulic control valve unit 6 receives a plurality of signals indicative of an accelerator opening degree, the transmission ratio of CVT 3, the rotational number of input shaft 13, a primary pulley pressure, and the like. Hydraulic control valve unit 6 controls the  
30 transmission ratio of CVT 3 by supplying pulley clamping pressure CP to primary and secondary pulley cylinder chambers 33 and 37 based on the input signals.



[0024] FIG. 2 shows a hydraulic circuit used in the first embodiment of the hydraulic control system. As illustrated in FIG. 2, pressure regulator valve 40 is connected to oil pump 8 via oil passage 41. Pressure regulator valve 40  
5 regulates a discharge pressure as line pressure (pulley clamping pressure), which is produced from oil pump 8. Oil passage 42 is communicated with oil passage 41 and supplies the pulley clamping pressure to primary pulley cylinder chamber 33 and secondary pulley cylinder chamber 37. Oil  
10 passage 43 is communicated with oil passage 42 and supplies an initial pressure to pilot valve 50.

[0025] An oil pressure drained from pressure regulator valve 40 is supplied to clutch regulator valve 60 via oil passage 46. Oil passage 46 is communicated with oil passage  
15 44 which is communicated with oil passage 42 and has orifice 45. Clutch regulator valve 60 regulates the oil pressure in oil passage 46 and the oil pressure in oil passage 44 and supplies a forward clutch applying pressure to forward clutch 25 via oil passage 61, a select switching valve and a  
20 select control valve. With this arrangement, the forward clutch applying pressure is regulated smaller than the pulley clamping pressure.

[0026] Pilot valve 50 controls the oil pressure at a constant value and supplies the oil pressure to a select  
25 switching solenoid valve and a lockup solenoid valve via oil passage 51. The output pressure supplied to the select switching solenoid valve is supplied to a select switching valve and controls the operation of the select switching valve. The output pressure supplied to the lockup solenoid  
30 valve is supplied to the select switching valve.

[0027] Torque converter regulator valve 70 is supplied with the oil pressure drained from clutch regulator valve 60 via oil passage 71. Torque converter regulator valve 70

regulates the oil pressure in oil passage 71 and the oil pressure in oil passage 72. The oil pressure in oil passage 72 is supplied to lockup control valve 80 which supplies the oil pressure to a release side of torque converter 1 via oil passage 81. The oil drained from torque converter regulator valve 70 is supplied to lockup control valve 80 via oil passage 73 and then to an apply side of torque converter 1 via oil passage 82. The oil pressure drained from lockup control valve 80 is supplied to oil cooler 90 via oil passage 83. The oil passing through oil cooler 90 is cooled and supplied to lubrication parts of CVT 3 to be lubricated, and then returned to an oil pan, not shown. For example, the oil cooled is supplied to belt lubricating nozzle 94 and gear lubricating nozzle 95 via oil passage 91, oil filter 92 and oil passage 93. The oil supplied to belt lubricating nozzle 94 is injected to belt 34 of CVT 3. The oil supplied to gear lubricating nozzle 95 is injected to differential gear 96.

[0028] Referring now to FIG. 3, a control logic of the first embodiment of the system or method according to the present invention is explained. The control logic is executed by CVT controller 9. Logic flow starts and goes to block 101 where it is determined whether the oil temperature in CVT 3 is high. Namely, at block 101, a determination as to whether the oil temperature in CVT 3 is not less than a predetermined value is made based on oil temperature signal Toil from oil temperature sensor 11. In this embodiment, the predetermined value is in a range of 120°C - 130°C. When the answer to block 101 is yes, the logic flow proceeds to block 102. At block 102, a determination as to whether CVT 3 is in the manual transmission mode is made based on signal MM/AM from transmission mode sensor 16. When the answer to block 102 is no, indicating that CVT 3 is in the automatic

transmission mode, the logic flow proceeds to block 103. At block 103, a determination as to whether ABS is in the operating condition is made based on signal ABS ON/OFF from ABS sensor 17. When the answer to block 103 is no, the logic flow proceeds to block 104.

[0029] At block 104, required belt lubricating oil flow amount  $Q_{br}$  which is an oil flow amount required for lubricating belt 34 of CVT 3 is calculated based on input torque  $T_{Qin}$ , primary pulley speed  $N_p$  and pulley speed ratio PSR. Input torque  $T_{Qin}$  is calculated based on throttle opening degree signal TVO from throttle position sensor 10. Pulley speed ratio PSR is calculated based on primary pulley speed signal  $N_p$  from primary pulley speed sensor 4 and secondary pulley speed  $N_s$  from secondary pulley speed sensor 5. Specifically, the calculation of required belt lubricating oil flow amount  $Q_{br}$  is performed using a table as shown in FIG. 4.

[0030] The table of FIG. 4 has maps No. 1 to No. 9 corresponding to differences in input torque  $T_{Qin}$ , pulley speed ratio PSR and primary pulley speed  $N_p$ . One map is selected from maps No. 1 to No. 9 on the basis of input torque  $T_{Qin}$ , primary pulley speed  $N_p$  and pulley speed ratio PSR. For instance, when input torque  $T_{Qin}$  is large, pulley speed ratio PSR is  $b$ , and primary pulley speed  $N_p$  is  $B$ , map No. 2 is selected. FIG. 5 illustrates map No. 2 showing a relationship between required belt lubricating oil flow amount  $Q_{br}$  and primary pulley speed  $N_p$ . Required belt lubricating oil flow amount  $Q_{br}$  is retrieved from map No. 2 based on primary pulley speed  $N_p$ .

[0031] The logic flow proceeds to block 105 where required cooler oil flow amount  $Q_{cr}$  which is an oil flow amount required to be supplied to oil cooler 90 is calculated from required belt lubricating oil flow amount

Qbr calculated at block 104, on the basis of a predetermined oil distribution ratio. Here, the predetermined oil distribution ratio means a ratio of an oil flow amount to be supplied from oil cooler 90 to a belt lubricating oil supply passage formed by oil passage 93 and belt lubricating nozzle 94, to an oil flow amount to be supplied from oil cooler 90 to a lubricating oil supply path which is located downstream of oil cooler 90 and includes oil passage 91, the belt lubricating oil supply passage and gear lubricating nozzle 95. In other words, the predetermined oil distribution ratio is a ratio of required belt lubricating oil flow amount Qbr to an oil flow amount passing through oil cooler 90. In this embodiment, the predetermined oil distribution ratio is about 1:2.

[0032] The logic flow proceeds to block 106 where required cooler input pressure Pcin which is an oil pressure required to be supplied to oil cooler 90 is calculated based on required cooler oil flow amount Qcr calculated at block 105. Specifically, required cooler input pressure Pcin is retrieved from a map as shown in FIG. 6, based on required cooler oil flow amount Qcr calculated at block 105. FIG. 6 illustrates an example of the map showing a relationship between required cooler oil flow amount Qcr and required cooler input pressure Pcin which is established corresponding to line pressure LP.

[0033] The logic flow proceeds to block 107 where current minimum speed Nmin1 of oil pump 8, namely, engine minimum speed, is calculated based on required cooler input pressure Pcin calculated at block 106. Specifically, current minimum speed Nmin1 is retrieved from a map as shown in FIG. 7, based on required cooler input pressure Pcin calculated at block 106. The map of FIG. 7 shows a relationship between required cooler input pressure Pcin and oil pump minimum

speed  $N_{min}$  which established for each oil temperature  $Toil$  and each line pressure  $LP$ .

[0034] The logic flow proceeds to block 108. At block 108, oil pump minimum speed  $N_{min}$  is determined by comparing  
5 current minimum speed  $N_{min1}$  with previous minimum speed  $N_{min0}$  calculated in the control routine previously executed. Specifically, by the comparison between current minimum speed  $N_{min1}$  and previous minimum speed  $N_{min0}$ , a larger one thereof is selected and determined as desired oil pump  
10 minimum speed  $N_{min}$ . The logic flow proceeds to block 109. At block 109, control signal  $CS$  is outputted to hydraulic control valve unit 6 to change the transmission ratio of CVT 3 and control and hold the engine speed, namely, the oil pump speed, at minimum speed  $N_{min}$ . The logic flow then goes  
15 to end.

[0035] When the answer to block 101 is no, the logic flow jumps to block 110 where previous minimum speed  $N_{min0}$  calculated in the previously executed control routine is cleared. The logic flow then goes to end. When the answer  
20 to block 102 is yes, indicating that CVT 3 is in the manual transmission mode, the logic flow jumps to block 110. When the answer to block 103 is yes, indicating that ABS is in the ON state, the logic flow jumps to block 110.

[0036] As explained above, in the first embodiment of the  
25 system and method, CVT controller 9 calculates required belt lubricating oil flow amount  $Q_{br}$  based on at least one of the following operating conditions:

- 1) input torque  $T_{Qin}$  of CVT 3;
- 2) primary pulley speed  $N_p$  of CVT 3; and
- 30 3) transmission ratio (pulley speed ratio) of CVT 3.

Therefore, the system and method of the first embodiment can suppress an unnecessary lubricating oil flow amount in comparison with the above-described conventional art which

calculates a required belt lubricating oil flow amount based on only oil temperature. This serves for alleviating load of an oil pump driving source such as an engine and preventing a rotational speed of the driving source from unnecessarily increasing under high oil temperature condition. Further, CVT controller 9 calculates required cooler input pressure  $P_{cin}$  based on required cooler oil flow amount  $Q_{cr}$  and determines oil pump minimum speed  $N_{min}$  based on required cooler input pressure  $P_{cin}$ , oil temperature  $T_{oil}$  and line pressure  $LP$ . The system and method of the first embodiment can determine oil pump minimum speed  $N_{min}$  with enhanced accuracy in comparison with the above-described conventional art.

[0037] Further, when CVT 3 is in the manual transmission mode, CVT controller 9 clears oil pump minimum speed  $N_{min0}$  determined in the previous control routine. This allows the control that assigns a priority to the operating condition requested by a vehicle operator.

[0038] Furthermore, since CVT controller 9 clears oil pump minimum speed  $N_{min0}$  calculated in the previously executed control routine upon ABS being in operation, the oil pump speed control can cause no interference with the ABS operation.

[0039] Maps or tables for calculating required belt lubricating oil flow amount  $Q_{br}$  are not limited to those shown in FIGS. 4 and 5. Maps shown in FIGS. 8 and 9 can also be used to calculate required belt lubricating oil flow amount  $Q_{br}$ . The map shown in FIG. 8 illustrates a relationship between input torque  $T_{Qin}$  and required belt lubricating oil flow amount  $Q_{br}$ . The map shown in FIG. 9 illustrates a relationship between pulley speed ratio  $PSR$  and required belt lubricating oil flow amount  $Q_{br}$ . Further,



required belt lubricating oil flow amount  $Q_{br}$  may be calculated using suitable mathematical expressions.

[0040] Referring to FIGS. 10 and 11, a second embodiment of the system and method according to the present invention will be explained hereinafter. FIG. 11 shows a control logic of the second embodiment which differs in block 210 and block 212 from the control logic of the first embodiment as shown in FIG. 3. The control logic of the second embodiment is also executed by CVT controller 9. When the answer to block 102 is yes, indicating that CVT 3 is in the manual transmission mode, the logic flow jumps to block 210. At block 210, oil pump minimum speed  $N_{min}$  required in the manual transmission mode is determined using a map shown in FIG. 10. The map of FIG. 10 illustrates a relationship between oil pump minimum speed  $N_{min}$  and required cooler input pressure  $P_{cin}$  in each of the manual transmission mode and the automatic transmission mode. Specifically, at block 210, oil pump minimum speed  $N_{min}$  required in the manual transmission mode is retrieved from the map of FIG. 10, based on required cooler input pressure  $P_{cin}$ . As illustrated in FIG. 10, minimum speed  $N_{min}$  in the manual transmission mode is set larger than that in the automatic transmission mode. Meanwhile, the map of FIG. 10 is only illustrative under typical conditions of oil temperature  $T_{oil}$  and line pressure  $LP$ . Although there is not shown in the map, as oil temperature  $T_{oil}$  and line pressure  $LP$  increase, oil pump minimum speed  $N_{min}$  is set larger, similar to FIG. 7.

[0041] At block 212, oil pump minimum speed  $N_{min}$  required in the automatic transmission mode is determined using the map shown in FIG. 10. Specifically, oil pump minimum speed  $N_{min}$  required in the automatic transmission mode is

retrieved from the map of FIG. 10, based on required cooler input pressure  $P_{cin}$ .

[0042] In the second embodiment, when CVT 3 is in the manual transmission mode, CVT controller 9 sets oil pump  
5 minimum speed  $N_{min}$  larger than in the automatic transmission mode. Owing to the determination of the larger minimum speed  $N_{min}$ , an oil flow amount required for lubrication can be obtained. The reason is as follows. Load in the manual transmission mode is usually larger than that in the  
10 automatic transmission mode. This causes increase in the required cooler oil flow amount and the lubricating oil flow amount, and increase in the oil flow amount that is used in the pulleys in order to enhance the transmission speed of the CVT. As a result, the oil pressure to be supplied to  
15 the oil cooler is reduced.

[0043] Although oil pump 8 is directly driven by the engine in the first and second embodiments, oil pump 8 may be driven by a motor.

[0044] This application is based on a prior Japanese  
20 Patent Application No. 2002-285500 filed on September 30, 2002. The entire contents of the Japanese Patent Application No. 2002-285500 is hereby incorporated by reference.

[0045] Although the invention has been described above by  
25 reference to certain embodiments of the invention, the invention is not limited to the embodiments described above. Modifications and variations of the embodiments described above will occur to those skilled in the art in light of the above teachings. The scope of the invention is defined with  
30 reference to the following claims.